

Final Exam (AMIE352-00, Spring 2014)

June 16, 2014. 4:30 pm – 5:45 pm

Prof. Youngmin You

1. Answer following questions: (6 points)

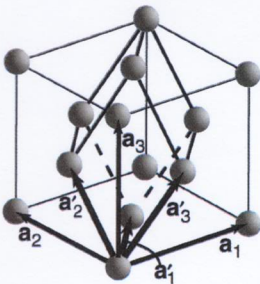
(1) Write the zone equation (Miller index (hkl)) for a $[221]$ zone (3 points).

$$2h + 2k + l = 0$$

(2) Which of these planes belong to the $[221]$ zone: $(\bar{1}\bar{1}0), (\bar{1}13), (0\bar{1}2), (\bar{1}32), (\bar{2}21), (\bar{1}\bar{1}4)$? (3 points)

$$(\bar{1}\bar{1}0), (\bar{1}\bar{1}2), (\bar{1}\bar{1}4) \\ (0\bar{1}2)$$

2. Shown below is the face-centered cubic lattice (cF), wherein we can define a primitive rhombohedral (R) unit cell. Answer following questions: (16 points).



(1) What is the transformation matrix for $cF \rightarrow R$? (3 points)

$$\alpha_{ij} = \frac{1}{2} \begin{pmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 1 & 0 & 1 \end{pmatrix}$$

(2) What are the reciprocal basis vectors in R ? (3 points)

Use this $\vec{a}_j'^* = \vec{a}_j^* \alpha_{ji}^{-1}$

$$= (\vec{a}_1^* \vec{a}_2^* \vec{a}_3^*) \begin{pmatrix} 1 & -1 & 1 \\ 1 & 1 & -1 \\ -1 & 1 & 1 \end{pmatrix}$$

$$\vec{a}_1'^* = \vec{a}_1^* + \vec{a}_2^* - \vec{a}_3^* \\ \vec{a}_2'^* = -\vec{a}_1^* + \vec{a}_2^* + \vec{a}_3^* \quad , \quad \vec{a}_3'^* = \vec{a}_1^* - \vec{a}_2^* + \vec{a}_3^*$$

(3) What is the direct metric tensor in R ? Use this for the direct metric tensor in cF (4 points):

$$\begin{pmatrix} a^2 & 0 & 0 \\ 0 & a^2 & 0 \\ 0 & 0 & a^2 \end{pmatrix} \Rightarrow g_{lk}$$

$$g_{ij}' = \alpha_{ik} g_{lk} \alpha_{jl} \\ = \frac{1}{2} \begin{pmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 1 & 0 & 1 \end{pmatrix} \cdot \begin{pmatrix} a^2 & 0 & 0 \\ 0 & a^2 & 0 \\ 0 & 0 & a^2 \end{pmatrix} \frac{1}{2} \begin{pmatrix} 1 & 0 & 1 \\ 1 & 1 & 0 \\ 0 & 1 & 1 \end{pmatrix} \\ = \frac{a^2}{4} \begin{pmatrix} 2 & 1 & 1 \\ 1 & 2 & 1 \\ 1 & 1 & 2 \end{pmatrix}$$

(4) What is the translation vector of $[001]_c$ after the $cF \rightarrow R$ transformation? (3 points)

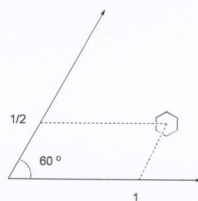
$$\begin{aligned}\vec{p}_i' &= \vec{p}_j \alpha_{ij}^{-1} \\ &= [001] \begin{pmatrix} 1 & -1 & 1 \\ 1 & 1 & -1 \\ -1 & 1 & 1 \end{pmatrix} = \underline{[-1 \ 1 \ 1]}\end{aligned}$$

(5) What is the Miller index of $(110)_c$ after the $cF \rightarrow R$ transformation? (3 points)

$$\begin{aligned}p_i' &= \alpha_{ij} p_j \\ &= \frac{1}{2} \begin{pmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 1 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 1 \\ \frac{1}{2} \\ \frac{1}{2} \end{pmatrix} \quad \therefore \underline{(2 \ 1 \ 1)}$$

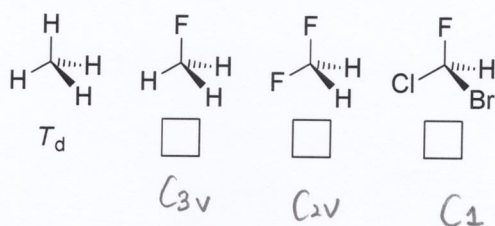
3. Calculate the W matrix for a $\pi/3$ rotation with respect to $(1, 1/2, 0)$ point in the hexagonal reference frame shown below. You don't need to calculate the matrix multiplication to have a single matrix; leave the matrices in their multiplication form. (7 points)

* Note that this is a hexagonal reference frame.

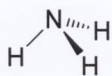


$$\begin{aligned}W &= W_{\text{translation}}(\text{origin} \rightarrow (1, \frac{1}{2}, 0)) \cdot W_{\pi/3 \text{ rotation}} \cdot W_{\text{translation}}((1, \frac{1}{2}, 0) \rightarrow \text{origin}) \\ &= \begin{bmatrix} 1 & 0 & 0 & 1 \\ 0 & 1 & 0 & \frac{1}{2} \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 0 & -1 & 0 & 0 \\ 1 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & -1 \\ 0 & 1 & 0 & -\frac{1}{2} \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}\end{aligned}$$

4. Substituted methanes can exist as four possible point groups. Identify their point groups (one correct answer = 3 points, two = 6 points; three = 9 points).



5. Shown below is an ammonia molecule. Answer following questions: (10 points)



(1) List symmetry elements of ammonia (2 points)

one C_3 axis
three σ_v

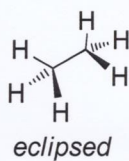
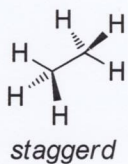
(2) List symmetry operations of ammonia (3 points)

$e, 3, 3^2, \sigma_{v(1)}, \sigma_{v(2)}, \sigma_{v(3)}$ *should be distinguishable ($\sigma_v, \sigma_v', \sigma_v''$)*
 $(C_3) (C_3^2)$

(3) What is the point group of ammonia? (5 points)

C_{3v}

6. Ethane (C_2H_6) can exist as two stable conformers, eclipsed and staggered forms. (16 points)



(1) List (or indicate in the molecular structures) the symmetry elements of the staggered (5 points) and eclipsed (5 points) conformers.

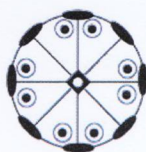
- staggered conformer: one C_3 axis, three C_2 axes, 3 σ_d , i , S_6
- eclipsed conformer: one C_3 axis, three C_2 axes, σ_h , 3 σ_d

(2) Identify the point groups of both conformers (3 point per each)

- staggered conformer: D_{3d}
- eclipsed conformer: D_{3h}

7. Shown below are stereographic projections of 3D crystallographic point groups. Determine their Hermann-Mauguin and Schönflies notations for each projection. (5 points per each; no partial points)

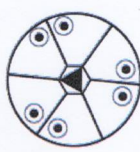
(1)



$4/mmm$ (H-M)

D_{4h} (S)

(2)



$\bar{6}m2$ (H-M)

D_{3h} (S)

(3)



$m\bar{3}$ (H-M)

T_h (S)

8. A 'polar point group' is a group in which there is at least one direction that has no symmetrically equivalent directions, and it happens only in non-centrosymmetric point groups with single rotation axes. (10 points)

(1) What are the highest-order point groups in the polar point groups? (5 points)

$4mm (C_{4v})$ and $6mm (C_{6v})$

(2) List all of the polar points groups. (5 points)

$4mm (C_{4v})$, $6mm (C_{6v})$, $6 (C_6)$, $4 (C_4)$, $3m (C_{3v})$, $3 (C_3)$ } ten, total.
 $mm2 (C_{2v})$, $m (C_s)$, $2 (C_2)$, $1 (C_1)$

9. In our last class, we had an invited speaker who gave a talk about 'organic molecules for photodynamic therapy'. (10 points)

(1) What is photodynamic therapy? (3 points)

It is a non-invasive therapy using photosensitizers that produce toxic singlet oxygen (1O_2) upon photoirradiation.

(2) Discuss about challenges that should be addressed for clinical applications of photodynamic therapy. (7 points)

- reduction in dark toxicity
- deep penetration of irradiation beam
- delivery of photosensitizers to cancerous region
- efficient photosensitization of 1O_2
- & etc ...